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PATENT

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UNITED STATES PATENT APPLICATION

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of

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INVENTOR: WILLIAM BOLICK

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A Citizen of the United States

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264 West State Road, #10

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PLEASANT GROVE, UTAH 84062

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for

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TRANSVERSELY MOVING CABLE CONTROL

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10078078.021502

**CROSS-REFERENCE TO RELATED APPLICATION**

This is a continuation of copending U. S. application Serial No. 08/902,987, filed on 07/30/1997.

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1 BACKGROUND OF THE INVENTION

2  
3 FIELD OF THE INVENTION

4 This invention relates to a control for transversely moving cables, especially those cables  
5 which operate such devices as the brakes on a bicycle.

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7 DESCRIPTION OF THE RELATED ART

8 There are many patented systems for controlling a cable to operate devices on a bicycle.

9 A significant number of these patents apply to devices which simply pull the cable from  
10 one end to exert a pulling force to control a device connected to the other end of the cable.  
11 Examples of this type of control are found in United States patent numbers 2,560,154; 4,005,613;  
12 and 5,584,210.

13 Also, a substantial number of patents cover devices which utilize a second cable to pull at  
14 an intermediate point on a first cable to create pulling forces on both ends of the first cable. To  
15 this category belong United States patent numbers 4,026,390 and 4,143,745; the embodiment  
16 represented by Figure 8 in United States patent number 4,653,613; and United States patent  
17 numbers 5,564,531 and 5,582,272. None of these patents, however, employ devices to maintain  
18 the first cable (at points other than the area where the second cable acts and the ends of such first  
19 cable) in substantially the original position of such first cable.

20 United States patent number 4,245,522 simply has a first lever connected by a first cable  
21 to a second lever which is connected to the cable which leads to the device to be operated.  
22 Moving either lever will then pull on a first end of the cable leading to the device to be operated  
23 by the consequent pull by the second end of such cable.

24 The control invention of United States patent number has a lever at each upper end of a  
25 Y-shaped cable so that using either lever to pull its associated segment of the cable will create a  
26 pull at the bottom of the cable to operate a device.

27 A sheath designated an "outer cable" covers an "inner cable" in the invention of United  
28 States Patent number 4,901,595. At an intermediate point the sheath is divided perpedicularly to  
29 its length. The divided segment nearer the device to be controlled is held in place while the other  
30 segment is rotated away from the segment nearer the device, thereby pulling on the inner cable  
31 and creating a pull on the end of the cable which operates a device.

1           Finally, the invention of United States patent no. 5,540,304 utilizes a first cable attached  
2 by a first pulley to a lever in order to move such lever and thereby to create a mechanical  
3 advantage by moving a second pulley that is attached to the lever at a position farther from the  
4 pivot point than is the first pulley. This second pulley then pulls on a second cable at an  
5 intermediate point. The segments of the second cable must, however, be parallel to one another  
6 as they depart from the second pulley.

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1                                    **BRIEF DESCRIPTION OF THE DRAWINGS**

2                    Figure 1 illustrates an embodiment of the Transversely Moving Cable Control which  
3 differs from the preferred embodiment only in the fact that the pivot for the pulley that transmits  
4 the transverse force to the cable is not adjustable.

5                    Figure 2 shows the preferred embodiment for the Transversely Moving Cable Control.

6                    Figure 3 depicts an alternate embodiment of the Transversely Moving Cable Control.

7                    Figure 4 portrays the embodiment of Figure 1 where a first end of the cable has been  
8 anchored just beyond the exit aperture of the lever.  
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## 1                    DESCRIPTION OF THE PREFERRED EMBODIMENT

2                    As illustrated in Figure 1, the Transversely Moving Cable Control has a lever 1 rotatably  
3 attached to a hollow base plate 2 with a pivot 3.

4                    When the lever 1 has been rotated into the base plate 2 to the maximum extent possible,  
5 the cable 4 follows its original path. As the lever 1 is rotated outward from the base plate 2, the  
6 cable 4, between a cable guide 7 and an exit 8 from the lever 1, *i.e.*, the portion of the cable 4  
7 which is within the transversely moving cable control, is moved substantially transversely to the  
8 original path of the cable 4, preferably by a pulley 9 attached to the lever 1 across which pulley 9  
9 the cable 4 runs, although a simple projection would suffice for this purpose, while the cable  
10 guide 7 and the exit 8 maintain the segments which lie outside the cable guide 7 and the exit 8,  
11 *i.e.*, the outer segments of the cable 4, in substantially the original positions of such segments of  
12 the cable 4. If a first end 5 of the cable 4 is anchored, such outward rotation of the lever 1 draws  
13 a second end 6 of the cable 4 longitudinally closer to the Transversely Moving Cable Control.  
14 Even, however, if the first end 5 of the cable 4 is not anchored, greater friction is encountered by  
15 the cable 4 within the lever 1 than within the cable guide 7 that is preferably rotatably attached to  
16 the base plate 2 so that generally only the second end 6 of the cable 4, and not the first end 5, is  
17 drawn closer to the Transversely Moving Cable Control. (As a practical matter, though, the first  
18 end 5 of the cable 4 is always anchored, either at the exit 8 for the cable 4 from the lever 1 or at  
19 some point farther from the exit 8 when used with a bicycle. And, in fact, the exit 8 could be  
20 eliminated and methods that are well known in the art could be used to adapt the lever for  
21 attachment of the first end 5 of the cable 4, such as simply enlarging the cable 4 just beyond the  
22 exit 8 outside the lever 1, as illustrated in Figure 4. )

23                    Similarly, as the lever 1 is allowed to rotate into the base plate 2, the cable 4 is moved  
24 transversely closer to the original path of the cable 4 so that the second end 6 of the cable 4 is  
25 allowed to move longitudinally farther from the Transversely Moving Cable Control.

26                    The distance which the cable 4 is moved--and, consequently, the mechanical advantage  
27 of the Transversely Moving Cable Control--can be increased either by having the pulley 9  
28 removably attached to the lever 1 and replacing the original pulley 9 with a pulley 9 having a  
29 greater diameter than the original pulley 9 or by moving the pivot 10 of the pulley 9 farther from  
30 the pivot 3 within the channel 26, which in the preferred embodiment of the Transversely

1 Moving Cable Control exists--as portrayed in Figure 2, within the lever 1, so that when the lever  
2 1 is rotated outward from the base plate 2, the pulley 9 will be farther from the original path of  
3 the cable 4. (The pivot 10 can be released, moved within the channel 26, and releasably fastened  
4 at another location within the channel 26 by using techniques which are well known in the art.)

5 A second major embodiment of the Transversely Moving Cable Control is depicted in  
6 Figure 3.

7 The cable 11 runs through two cable guides 12. The cable guides 12 are preferably  
8 pivotally mounted in a substantially U-shaped housing 13. One cable guide 12 is mounted,  
9 preferably pivotally, near a first end 14 of a first leg 15 of the U-shaped housing 13. The other  
10 cable guide 12 is mounted, preferably pivotally, near a first end 16 of a second leg 17 of the U-  
11 shaped housing 13. The cable guides 12 maintain the segments of the cable 11 which are  
12 outside the housing 13 and, therefore, outside the transversely moving cable control, in  
13 substantially the original positions of such segments of the cable 11. (The cable guides 12 are  
14 preferable but could be replaced by apertures near the first end 14 of the first leg 15 and near the  
15 first end 16 of a second leg 17.)

16 A secondary cable 18 passes through an aperture 19 beginning in the second end 20 of  
17 the U-shaped housing 13 and extends into the space between first leg 15 and second leg 17 of the  
18 U-shaped housing 13 before being attached to a block 21. The cable 11 passes through the block  
19 21 between the point of attachment of the secondary cable 18 and a pulley 22. (Although pulleys  
20 are preferable since they reduce friction, any time a pulley is mentioned such pulley could be  
21 replaced by a stationary cylinder or other cable displacement device.)

22 As the block 21 is drawn by the secondary cable 18 toward the aperture 19, the portion of  
23 the cable 11 which is within the transversely moving cable control, specifically within the  
24 housing 13, is moved substantially transversely to the original path of the cable 11. Since both  
25 cable guides 12 are identical, both the first end 23 and the second end 24 of the cable 11 will be  
26 pulled longitudinally closer to the U-shaped housing 13. If only the first end 23 of the cable 11  
27 is anchored, only the second end 24 of the cable 11 will be pulled longitudinally closer to the U-  
28 shaped housing 13. Just as with the first embodiment of the Transversely Moving Cable Control,  
29 the first end 23 of the cable can be anchored at a first end 25 of the cable guide 12 in the first leg  
30 15 of the U-shaped housing 13 (or, if the cable guide 12 in the first leg 15 were eliminated,



1 simply to the first leg 15, itself, at a point adapted for attachment of the cable 11) or at some  
2 point farther from the first end 25 of the cable guide 12.

3 Similarly, as the block 21 is allowed to move farther from the aperture 19, the cable 11 is  
4 permitted to move transversely closer to the original path of the cable 11, thereby permitting the  
5 unanchored end 24 (or unanchored ends 23, 24) of the cable 11 to move longitudinally farther  
6 from the U-shaped housing 13.

7 As long as the first end 23 and the second end 24 of the cable 11 are not parallel to one  
8 another, the larger the diameter of the pulley 22, the greater will be the movement of the end 24  
9 or both ends 23, 24 of the cable 11 and, consequently, the greater will be the mechanical  
10 advantage of the Transversely Moving Cable Control.

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